

Amendments to the Claims:

Claim 3 is amended and claims 10 to 18 are added as set forth hereinafter.

Listing of Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application.

1. (Original) A method for controlling a drive unit of a vehicle, the method comprising the steps of:

adjusting an output quantity of said drive unit in dependence upon desired value input quantities; and,

5 to make the adjustment of said output quantity, forming a desired value which considers said desired value input quantities in a sequence of their priorities.

2. (Original) The method of claim 1, wherein, when forming said desired value, the method comprises the further step of considering said desired value input quantities starting with the desired value input quantity having the lowest priority.

3. (Currently Amended) The method of claim 1, ~~comprises~~ comprising the further step of coupling said desired value input quantities to different priorities, respectively.

4. (Original) The method of claim 1, wherein said desired value

input quantities limit said desired value or shift said desired value by an additive amount.

5. (Original) The method of claim 1, wherein a priority is permanently assigned to each one of said desired value input quantities.

6. (Original) The method of claim 1, wherein a priority is variably assigned to each one of said desired value input quantities.

7. (Original) The method of claim 6, wherein said priorities are assigned in dependence upon the operating state of said vehicle.

8. (Original) The method of claim 1, wherein different types of desired value input quantities are considered by different modules; and, the same types of desired value input quantities are each considered by a single module for forming said desired value.

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9. (Original) The method of claim 1, wherein a desired torque is selected as said desired value.

10. (New) A method for controlling a drive unit of a vehicle, the method comprising the steps of:

adjusting an output quantity of said drive unit in dependence upon desired quantity prescriptions; and,

5           to make the adjustment of said output quantity, forming a desired quantity which considers said desired quantity prescriptions in a sequence of their priorities.

11. (New) The method of claim 10, wherein, when forming said desired quantity, the method comprises the further step of considering said desired quantity prescriptions starting with the desired quantity prescription having the lowest priority.

12. (New) The method of claim 10, comprising the further step of coupling said desired quantity prescriptions to different priorities, respectively.

13. (New) The method of claim 10, wherein said desired quantity prescriptions limit said desired quantity or shift said desired quantity by an additive amount.

14. (New) The method of claim 10, wherein a priority is permanently assigned to each one of said desired quantity prescriptions.

15. (New) The method of claim 10, wherein a priority is variably assigned to each one of said desired quantity prescriptions.

16. (New) The method of claim 15, wherein said priorities are assigned in dependence upon the operating state of said vehicle.

17. (New) The method of claim 10, wherein different types of  
desired quantity prescriptions are considered by different  
modules; and, the same types of desired quantity prescriptions  
are each considered by a single module for forming said desired  
5 quantity.

18. (New) The method of claim 10, wherein a desired torque is  
selected as said desired quantity.